UNSUPERVISED PERFORMANCE EVALUATION OF RESULTS

1) Liu and Yang's evaluation function:

$$F = \sqrt{N} \sum_{j=1}^{N} \frac{e_j^2}{\sqrt{S_j}}$$

where N is number of obtained regions after segmentation, S_j - area of region j and e_j^2

(2)

- squared color error (or the gray level) that is calculated as

$$e_j^2 = \sum_{k \in S_j} (x_k - \overline{x})^2$$

where x_k is the gray level of the pixel, and the \overline{x} means gray level of the region.

2) Borsotti, Campadelli and Schettini **function F'**, to improve upon Liu and Yang's method:

$$F' = \frac{1}{1000 \cdot S_{I}} \sqrt{\sum_{a=1}^{MaxArea} [N(a)]^{1+1/a} \sum_{j=1}^{N} \frac{e_{j}^{2}}{\sqrt{S_{j}}}}$$

were S_I – represents the image surface;

N(a) – denote the number of regions in the segmented image having an area exactly *a*; MaxArea – is the area of the largest region in segmented image.

3) Borsotti et al. criterion

$$Q = \frac{1}{10000 \cdot S_{I}} \sqrt{N} \sum_{j=1}^{N} \left(\frac{e_{j}^{2}}{1 + \log S_{j}} + \left(\frac{N(S_{j})}{S_{j}^{2}} \right)^{2} \right)$$

were $N(S_j)$ – denote the number of regions in the segmented image having an area exactly S_j

4) Intra-region uniformity criterion of Levine and Nazif [13]:

Lev =
$$\sum_{j} \sum_{x \in R_j} \left(f(x) - \frac{1}{S_j} \sum_{x \in R_j} f(s) \right)^2 = \sum_{j} \frac{\sigma_j^2}{C}$$

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f(x) – the intensity of pixel x

C-normalized coefficient, equal to the maximum possible variance

$$C = \frac{(f_{max} - f_{min})^2}{2}$$

5) Entropy-based evaluation method [12]

As the authors say the entropy is a measure of the disorder within a region and is a natural characteristic to incorporate into a segmentation evaluation method.

The entropy for region *j* is defined as:

$$H_{v}(R_{j}) = -\frac{L_{j}(m)}{S_{j}}\log\frac{L_{j}(m)}{S_{j}}$$

were $L_j(m)/S_j$ represents the probability that a pixel in region R_j has a luminance value of *m*.

The notation $H_v(R_j)$ was simplified to $H(R_j)$ with the default feature v being luminance. H. Zhang et al. define the expected region entropy of image *I*:

$$H_r(I) = \sum_{j=1}^{N} \left(\frac{S_j}{S_i}\right) H(R_j),$$

and the layout entropy:

$$H_{l}(I) = -\sum_{j=1}^{N} \left(\frac{s_{j}}{s_{i}}\right) \log \frac{s_{j}}{s_{I}}.$$

They propose to combine the both the layout entropy and the expected entropy in measuring the effectiveness of a segmentation method:

$$\mathsf{E} = \mathsf{H}_{\mathsf{l}}(\mathsf{I}) + \mathsf{H}_{\mathsf{r}}(\mathsf{I}).$$